

Detecting Emergent Interference in Integration of Multiple Self-Adaptive Systems

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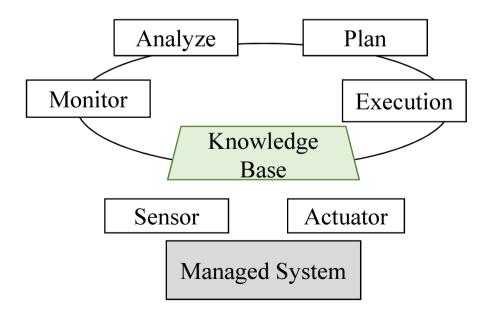
Outline

- Background
- Detecting Emergent Interference via Formal Verification
 - Modeling execution environment
 - Modeling self-adaptive systems
 - Verification of self-adaptive systems
 - Modeling and verifying SoS
- Conclusion and Future Work



Background

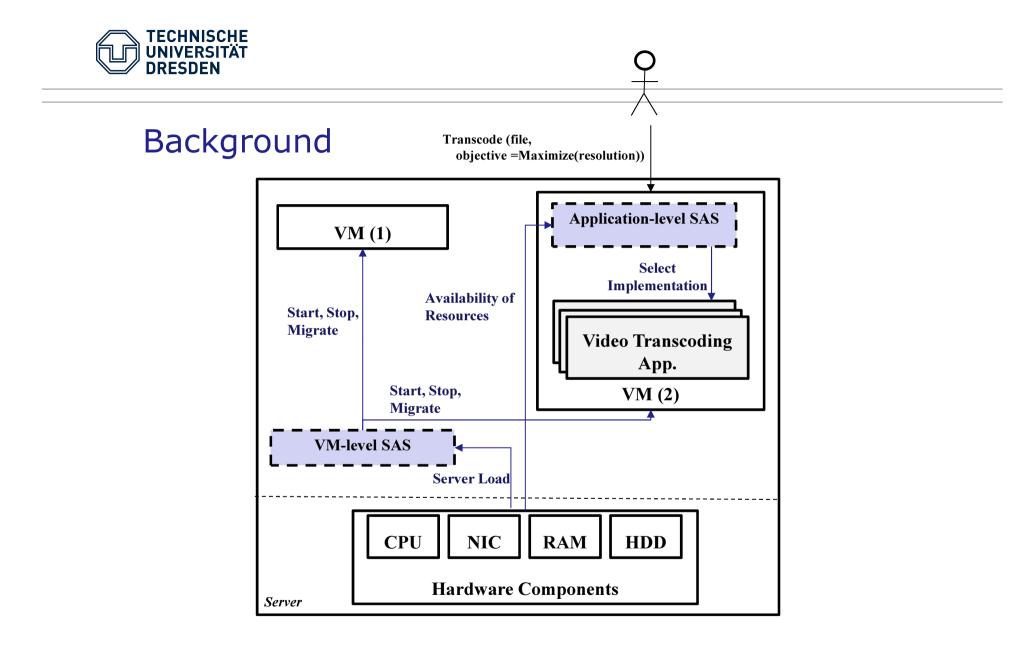
- Self-adaptive software systems (SAS's) are characterized by their ability to adapt according to changes in their environment.
- MAPE-K model is widely adopted to design and implement SAS's as a feedback control loop.





Background

- Within the context of the HAEC (Highly Adaptive Energy-efficient Computing) project, different research teams are investigating various kinds of SAS at different layers:
 - operating systems, database management systems, application software and virtual machines.
- The common goal of these SAS's is to improve the energy-utility of the system:
 - The system must serve the requests of users in an energy efficient way while fulfilling the desired utility objectives of the users.





Background

- Integrating multiple SAS's, which are developed and managed independently, is a novel example of SoS.
 - Is there any <u>emergent</u> interference as the result of such integration, which may negatively influence the overall energy-utility of the system?
- Emergent behavior is an effect that is caused from the interactions of multiple constituent entities.
 - The term "emergent" implies that it is very hard or even impossible to reduce the behavior to the behavior of individual constituent entities.
- Various types and categories of emergent behavior are defined in literature. Examples are:
 - Expected and desirable emergent behavior
 - Expected and undesirable emergent behavior
 - Unexpected and desirable behavior
 - Unexpected and undesirable emergent behavior

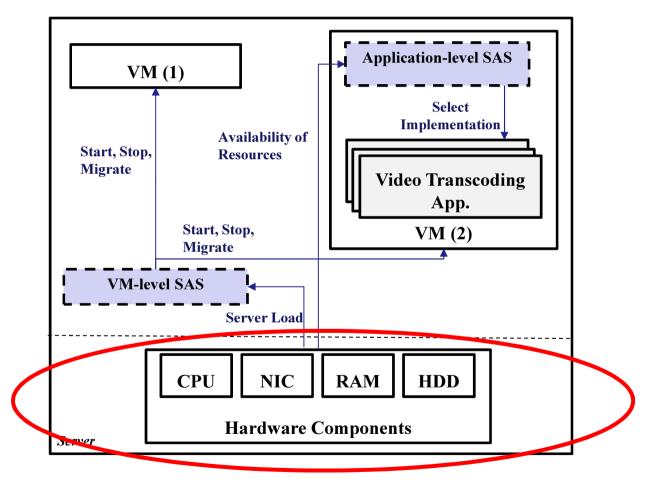


Detecting Emergent Interference via Formal Verification

- Due to the complexity of SAS's, there is an inevitable need to provide methodological and tool support to detect emergent interference.
- There are various methods to detect emergent behavior:
 - Variable-based
 - Event-based
 - > These require *a priori definition* of emergent behavior
- Adopting formal modeling and model checking to detect emergent behavior can be regarded as a combination of the variable-based and event-based methods.
 - The behavior of each constituent system is modeled as an event-based automaton, and the states of each automaton is represented via a set of variables.
 - A specific global state of the system, which is automatically detected by a model checker, is regarded as emergent behavior.

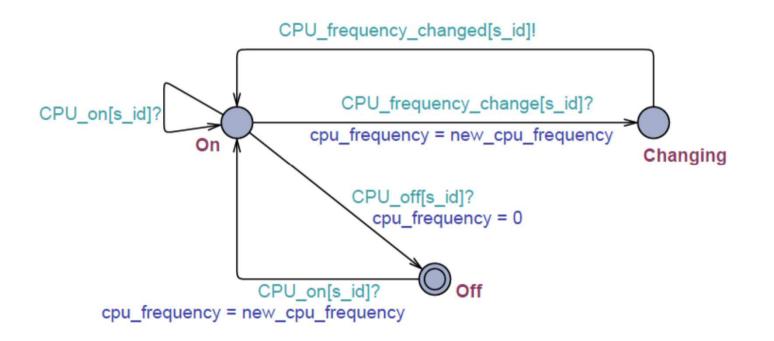


Step 1: Modeling Execution Environment



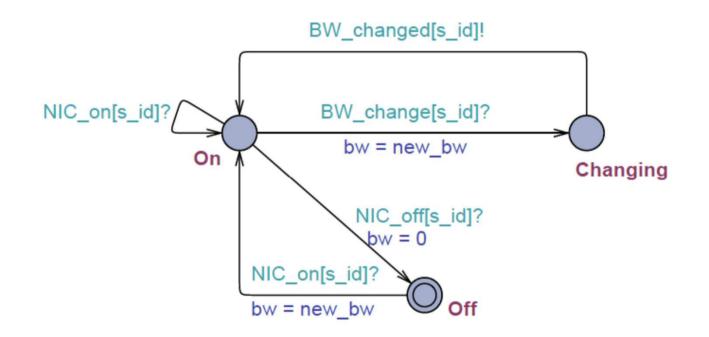


Step 1: Modeling Execution Environment (CPU)



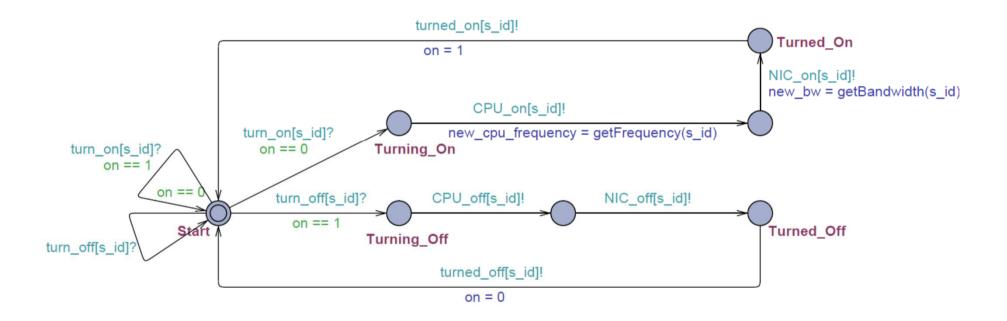


Step 1: Modeling Execution Environment (NIC)



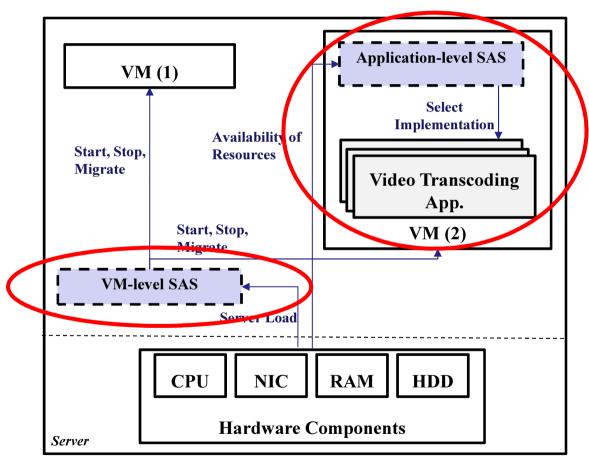


Step 1: Modeling Execution Environment (Server)



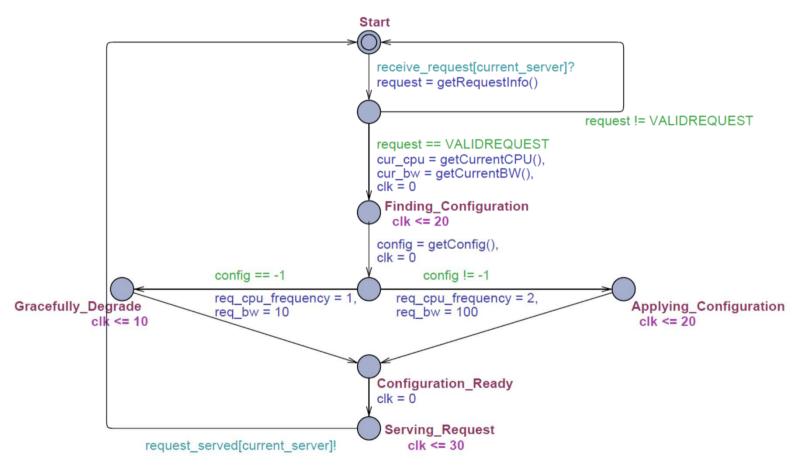


Step 2: Modeling Individual Self-adaptive Systems





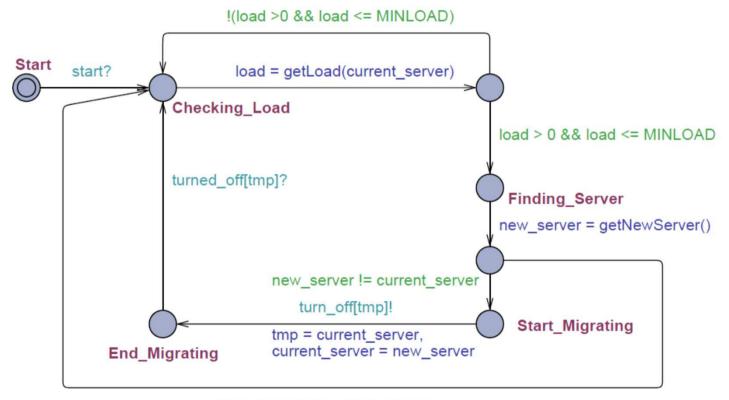
Step 2: Modeling Individual Self-adaptive Systems



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Step 2: Modeling Individual Self-adaptive Systems



new_server == current_server



Step 3: Verifying Individual Self-adaptive Systems

• If there is a valid request from user, the request will eventually be served by the application.

 $E <> (ApplicationLevelSAS.request == VALID_REQUEST and ApplicationLevelSAS.Serving_Request)$

• It will never be the case that while configuring the application with a new implementation, the CPU frequency and network bandwidth goes below the amount being used for selecting the implementation.

A[] not (ApplicationLevelSAS.Applying_Configuration and (CPU(current_server).cpu_frequency < cur_cpu or NIC(current_server).bw < cur_bw))

• It will never be the case that while serving a request, the CPU frequency and network bandwidth goes below the amount required for serving the request.

A[] not (ApplicationLevelSAS.Serving_Request and (CPU(current_server).cpu_frequency < req_cpu_frequency or NIC(current_server).bw < req_bw))



Step 3: Verifying Individual Self-adaptive Systems

• If a server is underutilized, and if a new server is found to migrate the VMs to, the migration will take place.

E<> (load >=0 and load <= MINLOAD and new_server != current_server and (VMLevelSAS.Start_Migrating imply VMLevelSAS.End_Migrating))



Step 4: Detecting Emergent Interference

• Defining an SoS in UPPAAL:

system

CPU, NIC, Server, ApplicationLevelSAS, VMLevelSAS, RuntimeScenario;

• Detecting emergent interference:

 $\mathbf{A} \models \rho \text{ and } (\mathbf{A} \otimes \mathbf{B} \otimes \dots) \not\models \rho$

• If a property is violated, model checkers give a counter-example trace. This trace can be adopted as a means to understand the potential interference among constituent systems.



Step 4: Detecting Emergent Interference

- Emergent interference (1):
 - If the VM-level SAS migrates a VM while application-level SAS is selecting an implementation of the application, there may be a case that the available resources in the new server is below the amount of resources that the application-level SAS is considering for selecting the best implementation.
- Emergent interference (2):
 - If the VM-level SAS migrates a VM while a selected implementation is serving a request, there may be a case that the available resources in the new server is below the amount of resources that is required by the implementation.
- The execution of the application takes more time and energy on the new server.



Conclusion and Future work

- Suitable methodological and tool support are needed to detect and represent emergent behavior.
 - Like any other kind of behavior, we require to provide both design-time and runtime support to detect and represent emergent behavior.
 - Formal modeling can be regarded a suitable mechanism to exhaustively comprehend the behavior of SoS.
 - However, it may not scale up properly.
- To cope with emergent interference, it is necessary to break the autonomic behavior of each constituent SAS, and provide means to coordinate their interactions.
 - Modularity of each SAS must be preserved.
 - Loose coupling must be achieved in the integrations.
 - Coordination protocols must also be modularized.
- We plan to adopt the concept of **event-based modularization** to modularly integrate multiple constituent systems with each other.
 - An event-based language is being implemented based on this concept.